

# XIAOFENG GAO

◇ Website: <https://xfgao.github.io/> ◇ E-mail: [xfgao@ucla.edu](mailto:xfgao@ucla.edu)

## EDUCATION

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**University of California, Los Angeles, CA, USA**  
*Ph.D. Candidate in Statistics*

*Sep. 2017 - Jun. 2022*  
Advisor: **Song-Chun Zhu**

**Fudan University, Shanghai, China**  
*B.Eng. in Electronic Engineering*

*Sep. 2013 - Jun. 2017*  
Overall GPA: 3.88/4.00; Ranking: **1/221**

## EXPERIENCE

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**Amazon**  
*Applied Scientist*

*Aug. 2022 - Present*  
Supervisors: Govind Thattai, Yadunandana Rao

Work on the Alexa Prize SimBot Challenge, which focuses on virtual assistants that can assist humans in completing real-world tasks by continuous learning and commonsense reasoning

**Amazon**  
*Applied Scientist Intern*

*Jun. 2021 - Sep. 2021*  
Supervisors: Qiaozi Gao, Gaurav Sukhatme, Govind Thattai

Present an embodied instruction following benchmark allowing an agent to actively ask questions  
Design and implement a pipeline to collect 50K task-relevant questions and answers on mTurk  
Propose a questioner-performer framework based on seq2seq and multi-modal Transformer  
Develop a reinforcement learning based algorithm to learn what questions to ask

**Honda Research Institute USA**  
*Research Intern*

*Jan. 2021 - Jun. 2021*  
Supervisors: Xingwei Wu, Teruhisa Misu

Study the effects of AR interface on drivers' object-wise situational awareness in autonomous vehicles  
Implement an AR-based user interface in a driving simulator based on Unreal Engine 4  
Design a novel SAGAT protocol with temporal variations to measure the driver's situational awareness  
Analyze the effect of AR interface in different conditions, e.g. object types, locations and traffic density

**Center for Vision, Cognition, Learning, and Autonomy, UCLA**  
*Graduate Student Researcher*

*Sep. 2017 - Present*  
Advisor: Song-Chun Zhu

Research interest: Explainable AI, Embodied AI, Human-Robot Interaction, Human-Machine Interaction, Computational Cognitive Science, Autonomous Driving

## PUBLICATIONS

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(\* indicates equal contribution)

R. Gong, Y. Zhao, **X. Gao**, J. Huang, Q. Wu, W. Ai, B. Jia, Z. Zhou, S.-C. Zhu, S. Huang. ARNOLD: A Benchmark for Language-Grounded Task Learning with Continuous States in Realistic Scenes. *CORL Workshop on Language and Robot Learning, 2022.*

L. Yuan\*, **X. Gao\***, Z. Zheng\*, M. Edmonds, Y. Wu, F. Rossano, H. Lu, Y. Zhu, S.-C. Zhu. In-situ Bidirectional Human-Robot Value Alignment. *Science Robotics, 2022.*

**X. Gao**, Q. Gao, R. Gong, K. Lin, G. Thattai, G. Sukhatme. DialFRED: Dialogue-Enabled Agents for Embodied Instruction Following. *IEEE Robotics and Automation Letters (RA-L), 2022.*

**X. Gao**, X. Wu, S. Ho, T. Misu, K. Akash. Effects of Augmented-Reality-Based Assisting Interfaces on Drivers' Object-wise Situational Awareness in Highly Autonomous Vehicles. *IEEE Intelligent Vehicles Symposium (IV), 2022.*

**X. Gao**, L. Yuan, T. Shu, H. Lu and S.-C. Zhu. Show Me What You Can Do: Capability Calibration on Reachable Workspace for Human-Robot Collaboration. *IEEE Robotics and Automation Letters (RA-L)*, 2022.

Z. Nan, J. Jiang, **X. Gao**, S. Zhou, W. Zuo, W. Ping, N. Zheng. Predicting Task-driven Attention via Integrating Bottom-up Stimulus and Top-down Guidance. *IEEE Transactions on Image Processing (T-IP)*, 2021.

**X. Gao\***, R. Gong\*, Y. Zhao, S. Wang, T. Shu, and S.-C. Zhu. Joint Mind Modeling for Explanation Generation in Complex Human-Robot Collaborative Tasks. *International Conference on Robot and Human Interactive Communication (RO-MAN)*, 2020.

**X. Gao**, R. Gong, T. Shu, X. Xie, S. Wang, and S.-C. Zhu. VRKitchen: an Interactive 3D Environment for Learning Real Life Cooking Tasks. *ICML Reinforcement Learning for Real Life Workshop*, 2019.

T. Shu, **X. Gao**, M. S. Ryoo, and S.-C. Zhu. Learning Social Affordance Grammar from Videos: Transferring Human Interactions to Human-Robot Interactions. *IEEE International Conference on Robotics and Automation (ICRA)*, 2017.

## SELECTED AWARDS & HONORS

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<b>Shanghai Outstanding Graduate</b> , Shanghai Municipal Education Commission	<i>Jun. 2017</i>
<b>Shanghai Government Scholarship</b> , Shanghai Municipal Education Commission	<i>Nov. 2016</i>
<b>First Prize, China Undergraduate Mathematical Modeling Contest</b>	<i>Nov. 2015</i>

## MEDIA COVERAGE

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**“A reachability-expressive motion planning algorithm to enhance human-robot collaboration”** *Feb. 2022*

*Covered by Ingrid Fadelli, Tech Xplore.*

**“VRKitchen: An interactive virtual environment to train and test AI agents”** *Mar. 2019*  
*Covered by Ingrid Fadelli, Tech Xplore.*

**“Robots taught to work alongside humans by giving high fives”** *Apr. 2017*  
*Covered by Matt Reynolds, New Scientist.*

## PROFESSIONAL SERVICE

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Journal Reviewer: UMUAI (2021-2022)

Conference Reviewer: IROS (2019), IEEE VR (2020), ICRA (2020), HRI (2020), CHI (2022), CogSci (2022), CSCW (2022)

Student Reviewer: UCLA Computer Science Graduate Admission (2018, 2020)

## TEACHING EXPERIENCE

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**UCLA STATS 10: Introduction to Statistical Reasoning** *Fall 2018*  
*Teaching Assistant*

## MENTORING

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Ran (Steven) Gong (2018 - 2019; Currently Ph.D. student in Computer Science at UCLA)

Phipson Lee (2018 - 2019; Master’s in Human-Computer Interaction, Carnegie Mellon University)

Ian Conceicao (2019 - 2020)

Jingwu (Frost) Zhang (2019 - 2020)

## TECHNICAL SKILLS

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### **Programming**

Tensorflow, Pytorch, C/C++, MATLAB, Python, R

### **Software & Tools**

Blender, Unreal Engine 4, Latex, ROS, SPSS, Qualtrics